

## Links

Wikipedia GPSDO - [https://en.wikipedia.org/wiki/GPS\\_disciplined\\_oscillator](https://en.wikipedia.org/wiki/GPS_disciplined_oscillator)

Shera's GPSDO - [http://www.rt66.com/~shera/index\\_fs.htm](http://www.rt66.com/~shera/index_fs.htm)  
[http://www.rt66.com/~shera/QST\\_GPS.pdf](http://www.rt66.com/~shera/QST_GPS.pdf)

Wikipedia PID - <https://sv.wikipedia.org/wiki/PID-regulator>

Poul Hennings simple description of a PI loop - <http://phk.freebsd.dk/time/20141018.html>

Pages 14-18 shows control loop of 1PPS locking of PRS10 (similar to the Arduino):  
<http://www.thinksrs.com/downloads/PDFs/Manuals/PRS10m.pdf>

On pages 26-31 you find ADEV and selection of time constants for a modern GPSDO FS740 with different oscillators and similar control loop as in the Arduino:  
<http://www.thinksrs.com/downloads/PDFs/Manuals/FS740m.pdf>

Arduino - <https://www.arduino.cc/>

ADEV - [https://en.wikipedia.org/wiki/Allan\\_variance](https://en.wikipedia.org/wiki/Allan_variance)

GPSDO simulator - <http://www.leapsecond.com/pages/gpsdo-sim/>

Timelab - <http://www.ke5fx.com/timelab/readme.htm>

Time nuts forum - <https://www.febo.com/mailman/listinfo/time-nuts>

uBlox u-center program - <https://www.u-blox.com/en/product/u-center-windows>

Lady heather program - <http://www.ke5fx.com/heather/readme.htm>

PICDIV - <http://www.leapsecond.com/pic/picdiv.htm>

GPS receiver M12 ADEV-MDEV charts - <http://www.leapsecond.com/pages/m12-adev/>

GPS receiver M12 sawtooth - <http://www.leapsecond.com/pages/m12/sawtooth.htm>

GPS receiver uBlox ADEV-MDEV charts - <https://www.eevblog.com/forum/projects/ocxo-stable-reference-and-control-voltages/50/>

Test of four GPSDO's - <http://www.leapsecond.com/pages/gpsdo/>

GPSDO HP Z3801 OCXO variations - <http://leapsecond.com/pages/z3801a-osc/>

FLL versus PLL See ke5fx for example - <http://www.ke5fx.com/gpscomp.htm>

## Appendix:

| Arduino GPSDO with 1ns TIC by Lars Walenius Rev. 3.0 170801 ID:1311 |      |       |      |        |         |         |    |      |        |       |                                    |      |       |      |        |  |
|---|------|-------|------|--------|---------|---------|----|------|--------|-------|------------------------------------|------|-------|------|--------|--|
| Type f1 <enter> to get help+info                                    |      |       |      |        |         |         |    |      |        |       |                                    |      |       |      |        |  |
| time  | ns   | dac   | temp | status | diff_ns | filtX10 | tc | filt | timer1 | temp1 |                                    |      |       |      |        |  |
| 0   | -390 | 34221 | 28.3 | WarmUp | 62      | 830     | 32 | 1    | 13838  | 28.1  | Five minute averages: TIC+DAC+temp |      |       |      |        |  |
| 1   | -384 | 34221 | 28.4 | WarmUp | 5       | 890     | 32 | 1    | 25021  | 28.1  | Now acquiring value: 0             |      |       |      |        |  |
| 2   | -382 | 34221 | 28.3 | WarmUp | 3       | 920     | 32 | 1    | 25031  | 28.1  |                                    |      |       |      |        |  |
| 3   | -378 | 34221 | 28.3 | WarmUp | 4       | 960     | 32 | 1    | 25042  | 28.1  | 0                                  | 0    | 0     | 0    |        |  |
| 4   | -377 | 34221 | 28.3 | WarmUp | 1       | 970     | 32 | 1    | 25042  | 28.1  | 1                                  | 0    | 0     | 0    |        |  |
| ....  |      |       |      |        |         |         |    |      |        |       |                                    |      |       |      |        |  |
| 292   | 418  | 34221 | 28.9 | WarmUp | -2      | 8980    | 32 | 1    | 25046  | 28.7  | 1143                               | 4982 | 34222 | 33.6 | Locked |  |
| 293   | 433  | 34221 | 29   | WarmUp | 15      | 9110    | 32 | 1    | 25046  | 28.7  |                                    |      |       |      |        |  |
| 294   | 431  | 34221 | 29   | WarmUp | -2      | 9090    | 32 | 1    | 25046  | 28.7  | TimeConst = 32 sec                 |      |       |      |        |  |
| 295   | 426  | 34221 | 28.9 | WarmUp | -4      | 9050    | 32 | 1    | 25046  | 28.7  | Prefilter = 1 sec                  |      |       |      |        |  |
| 296   | 441  | 34221 | 29   | WarmUp | 15      | 9180    | 32 | 1    | 25046  | 28.7  | Damping = 3.00 Gain = 80           |      |       |      |        |  |
| 297   | 434  | 34221 | 29   | WarmUp | -7      | 9120    | 32 | 1    | 25046  | 28.7  | Type f1<enter> to get help+info    |      |       |      |        |  |
| 298   | 446  | 34221 | 28.9 | WarmUp | 12      | 9230    | 32 | 1    | 25046  | 28.7  | Rev. 3.0 170801 ID:1311            |      |       |      |        |  |
| 299   | 437  | 34221 | 29   | WarmUp | -9      | 9150    | 32 | 1    | 25046  | 28.7  |                                    |      |       |      |        |  |
| 300   | 450  | 34221 | 28.9 | WarmUp | 12      | 9260    | 32 | 1    | 25046  | 28.8  | Five minute averages: TIC+DAC+temp |      |       |      |        |  |
| 301   | 441  | 35276 | 29   | NoLock | -9      | 9180    | 32 | 1    | 25018  | 28.8  | Now acquiring value: 1             |      |       |      |        |  |
| 302   | 440  | 35285 | 29   | NoLock | -1      | 9170    | 32 | 1    | 25018  | 28.8  |                                    |      |       |      |        |  |
| 303   | 439  | 35293 | 28.9 | NoLock | -1      | 9160    | 32 | 1    | 25018  | 28.8  | 0                                  | 5165 | 34221 | 28.6 |        |  |
| 304   | 432  | 35289 | 29   | NoLock | -7      | 9100    | 32 | 1    | 25018  | 28.7  | 1                                  | 0    | 0     | 0    |        |  |
| 305   | 407  | 35244 | 28.9 | NoLock | -25     | 8880    | 32 | 1    | 25018  | 28.7  | 2                                  | 0    | 0     | 0    |        |  |
| ....  |      |       |      |        |         |         |    |      |        |       |                                    |      |       |      |        |  |
| 523   | -21  | 34418 | 29.4 | NoLock | 10      | 4790    | 32 | 1    | 25016  | 29.2  | 1074                               | 4993 | 34216 | 33.3 | Locked |  |
| 524   | -31  | 34392 | 29.4 | NoLock | -10     | 4690    | 32 | 1    | 25016  | 29.2  | 1075                               | 4995 | 34216 | 31.7 | Locked |  |
| 525   | -23  | 34411 | 29.4 | NoLock | 8       | 4770    | 32 | 1    | 25015  | 29.2  | 1076                               | 4995 | 34216 | 33.1 | Locked |  |
| 526   | -16  | 34428 | 29.4 | NoLock | 7       | 4840    | 32 | 1    | 25016  | 29.2  | 1077                               | 4993 | 34216 | 33.8 | Locked |  |
| 527   | -30  | 34393 | 29.4 | NoLock | -14     | 4700    | 32 | 1    | 25015  | 29.2  | 1078                               | 4992 | 34216 | 33.2 | Locked |  |
| 528   | -24  | 34393 | 29.4 | Locked | 6       | 4703    | 32 | 16   | 25015  | 29.2  | 1079                               | 4994 | 34216 | 33.6 | Locked |  |
| 529   | -19  | 34394 | 29.3 | Locked | 5       | 4710    | 32 | 16   | 25016  | 29.2  | 1080                               | 4993 | 34216 | 33.4 | Locked |  |

Figure 1. Example of serial data pasted to Excel

```

Info and help - To get values for gain etc type f2 <enter>, f3 <enter> reads ADC3 and f4 <enter> EEPROM
Arduino GPSDO with 1ns TIC by Lars Walenius Rev. 3.0 170801 ID:1311

Typing a<value><enter> will set a new damping between between 0.50 and 10.00 set 50 to 1000
Typing b<value><enter> will set a new tempRef between 1 and 1023
Typing c<value><enter> will set a new tempCoeff set between 0 and 10000. Adding 10000 gives negative tc
Typing d<value><enter> will set a new dacValue between 1 and 65535
Typing e<value><enter> will erase the 3 hour storage in EEPROM if value 1 and all EEPROM if 22 (33 sets all EEPROM to FF)
Typing g<value><enter> will set a new gain between 10 and 65535
    gain = (65536/settable VCOrange in ppb) (eg. 100ppb DACrange gives gain=655)
Typing h<value><enter> will set hold mode and the entered dacValue if not h0 that uses the old
Typing i<value><enter> with value 1 will toggle ns decimal point else will toggle amount of information
Typing j<value><enter> Set temp sensor type 0=raw 1=LM35 2=10kNTC+68k 3=10kNTC+47k (second digit=adc1 eg 3x)
Typing l<enter> will set TIC linearization parameters min max square
    values 1-500 sets min to 0.1-50, values 800-1023 sets max, values 1024-1200 sets square to 0.024-0.200
Typing n<value><enter> will set ID number 0-65535 that is displayed
Typing o<value><enter> will set a new TIC_Offset between 200 and 1020 ns
Typing p<value><enter> will set a new prefilter div between 2 and 4
Typing r<enter> will set run mode
Typing s<value><enter> will save gain etc to EEPROM if value 1 and dacvalue if 2
Typing t<value><enter> will set a new time constant between 4 and 32000 seconds
Typing w<value><enter> will set a new warmup time between 2 and 1000 seconds

time ns dac temp status diff_ns filtX10 tc filt timer1 temp1
3642 -4 34413 32.3 Locked 3 4972 32 16 25016 32.7 39 0 0 0.0
3642 0 34413 32.4 Locked 4 4974 32 16 25016 32.7 40 0 0 0.0

```

Figure 2. f1 info and help

|              |      |                |      |             |      |                    |      |             |       |
|--------------|------|----------------|------|-------------|------|--------------------|------|-------------|-------|
| Gain         | 80   | Damping        | 3.00 | TimeConst   | 32   | FilterDiv          | 2    | TIC_Offset  | 500   |
| TempRef      | 280  | TempCoeff      | 0    | TICmin      | 12.0 | TICmax             | 1012 | Square comp | 0.100 |
| Warm up time | 300  | LockPPScounter | 3277 | MissedPPS   | 0    | TimeSinceMissedPPS | 3645 |             |       |
| ID_Number    | 1311 | Restarts       | 19   | Total hours | 450  |                    |      |             |       |

Figure 3. f2 serial prints some variables

```

EEPROM content:
restarts = 19
totalTime3h = 150
temperature_Sensor_Type = 53
ID_Number = 1311
TICmin = 120
TICmax = 1012
x2 = 100
TIC_Offset = 500
filterDiv = 2
warmUpTime = 300
damping = 300
tempRef = 280
tempCoeff = 0
dacValueOut = 34221
gain = 80
timeConst = 32
k = 6

```

Figure 4. f4 serial prints EEPROM contents

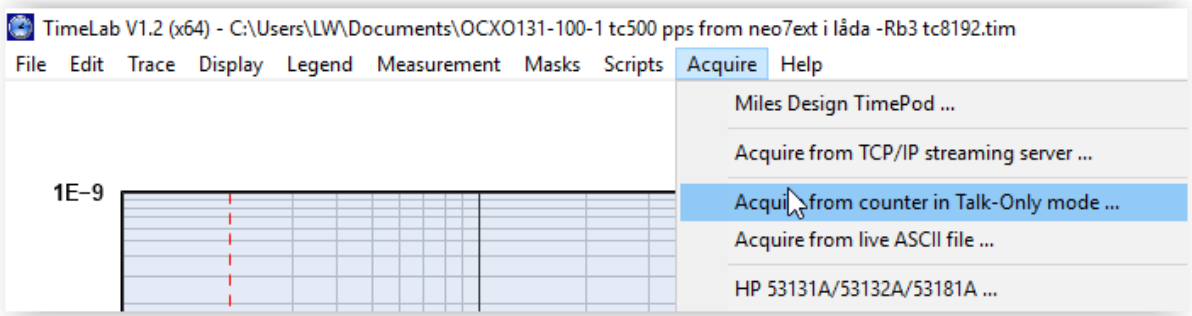


Figure 5. Acquire from Arduino serial port

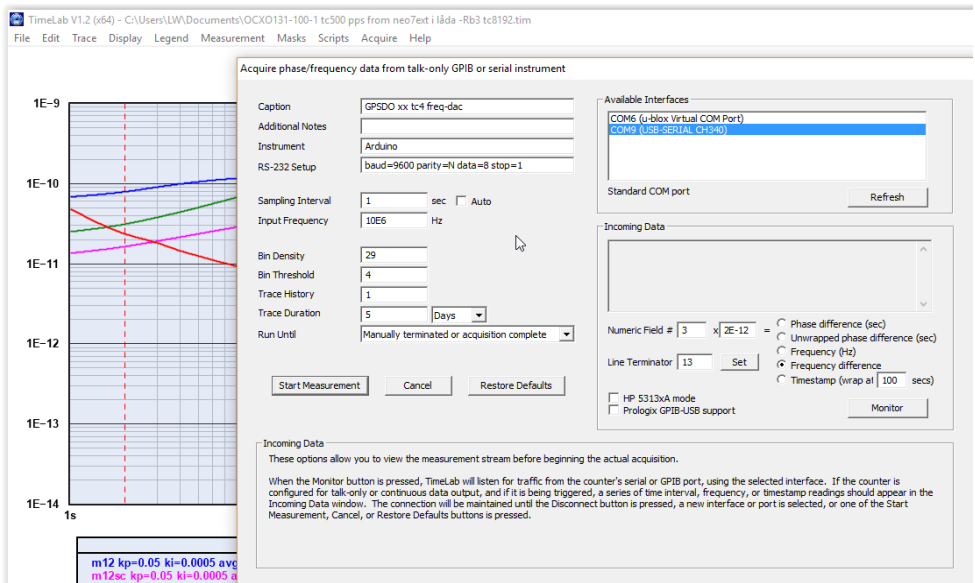


Figure 6. Acquire DAC value from Arduino serial port

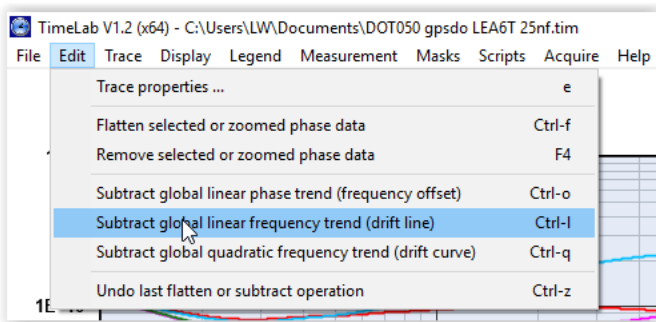


Figure 7. Subtract linear drift in Timelab